



TENSOR CHARACTER OF CONSTITUTIVE LAWS

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Contents

- 3D elasticity
- Tangent stiffness symmetry
- Spectral decomposition
- Invariants
- Isotropic material
- Hooke's law



3D Elasticity

Free energy existence

$$\exists \psi(\epsilon_{ij}) \quad \Rightarrow$$

$$\sigma_{ij} = \frac{\partial \psi}{\partial \epsilon_{ij}}$$



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Tangent stiffness

$$d\sigma_{ij} = \frac{\partial \sigma_{ij}}{\partial \epsilon_{11}} d\epsilon_{11} + \frac{\partial \sigma_{ij}}{\partial \epsilon_{12}} d\epsilon_{12} + \cdots + \frac{\partial \sigma_{ij}}{\partial \epsilon_{33}} d\epsilon_{33}$$



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4th order tensor

$$C_{ijkl} = \frac{\partial^2 \psi}{\partial \epsilon_{ij} \partial \epsilon_{kl}}$$

(Hessian)



Tangent stiffness symmetries

1. Minor symmetry

$$\sigma, \epsilon \text{ sym. } \underbrace{i \longleftrightarrow j, \quad k \longleftrightarrow l}_{6 \times 6 = 36}$$



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$$C_{ijkl} = C_{klij}, \quad ij \longleftrightarrow kl, \quad 21 \text{ coefficients}$$

(example: FE stiffness matrix)



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3. Material symmetry

isotropy group (E, ν)



Polar decomposition (1/2)

Let $[U]$ be 3×3 real symmetric matrix. Form the associated eigenproblem

$$[U]\{\varphi_k\} = \lambda_k\{\varphi_k\}, \quad \text{for } k = 1, 2, 3$$



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Property: $\lambda_k \in \mathbb{R}$, $\{\varphi_k\} \in \mathbb{R}^3$



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Orthonormal system

$$\{\varphi_i\}^T \{\varphi_j\} = \begin{cases} 1, & i = j \\ 0, & i \neq j \end{cases} = \delta_{ij} \quad (\text{Kronecker})$$



Polar decomposition (2/2)

Modal matrix: $[\Phi] = [\{\varphi_1\} \{\varphi_2\} \{\varphi_3\}]$, $[\Phi]^T[\Phi] = [I]$ (orthonormal)



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Block multiplication

$$[U][\Phi] = [[U]\{\varphi_1\} [U]\{\varphi_2\} [U]\{\varphi_3\}]$$



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$$[U] = [\Phi][\Lambda][\Phi]^T$$



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Block multiplication

$$[U][\Phi] = [[U]\{\varphi_1\} [U]\{\varphi_2\} [U]\{\varphi_3\}] = [\lambda_1\{\varphi_1\} \ \lambda_2\{\varphi_2\} \ \lambda_3\{\varphi_3\}] = [\Phi][\Lambda]$$

$$[U] = [\Phi][\Lambda][\Phi]^T$$

Theorem: $[U]$ sym+def $\iff \lambda_k > 0$



Note on quadratic forms

Example: energy of a linear system

$$P_2(x_1, x_2, \dots, x_n) = U_{ij}x_i x_j = \{x\}^T [U] \{x\}$$



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Matrix symmetry

$$U_{ij}x_i x_j = \dots U_{12}x_1 x_2 + U_{21}x_2 x_1 \dots = \dots (U_{12} + U_{21})x_1 x_2 \dots$$



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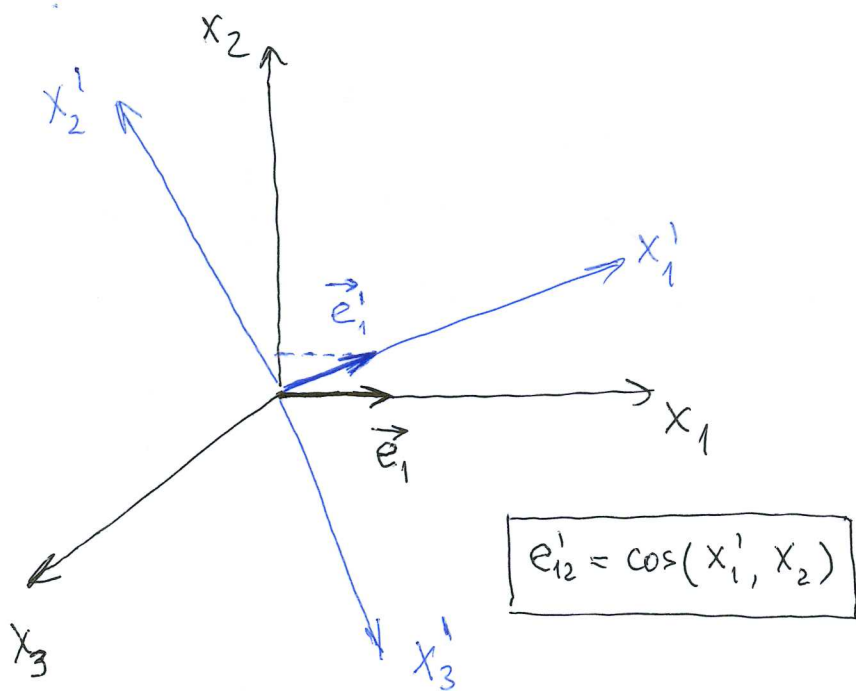
$$U_{ij}x_i x_j = \dots U_{12}x_1 x_2 + U_{21}x_2 x_1 \dots = \dots (U_{12} + U_{21})x_1 x_2 \dots$$

Convexity

$$\forall \{x\} \neq \{0\} : \{x\}^T [U] \{x\} > 0$$

We say $[U]$ is symmetric, positive definite (sym+def).

Cartesian system



column vector: $\{e'_1\} = \begin{Bmatrix} e'_{11} \\ e'_{12} \\ e'_{13} \end{Bmatrix}$

Orthogonal transformation

$$[A]: x \mapsto x', \quad [A]^T[A] = [I]$$

$$\{x'\} = [A]\{x\}$$

$$[A] = \begin{bmatrix} \underbrace{e'_{11} \quad e'_{12} \quad e'_{13}}_{\text{1st row} = \{e'_1\}^T} \\ \vdots \end{bmatrix}$$

Principal axes

Given a second order tensor

$$\tilde{\epsilon} \mapsto \epsilon_{ij}, [\epsilon]$$

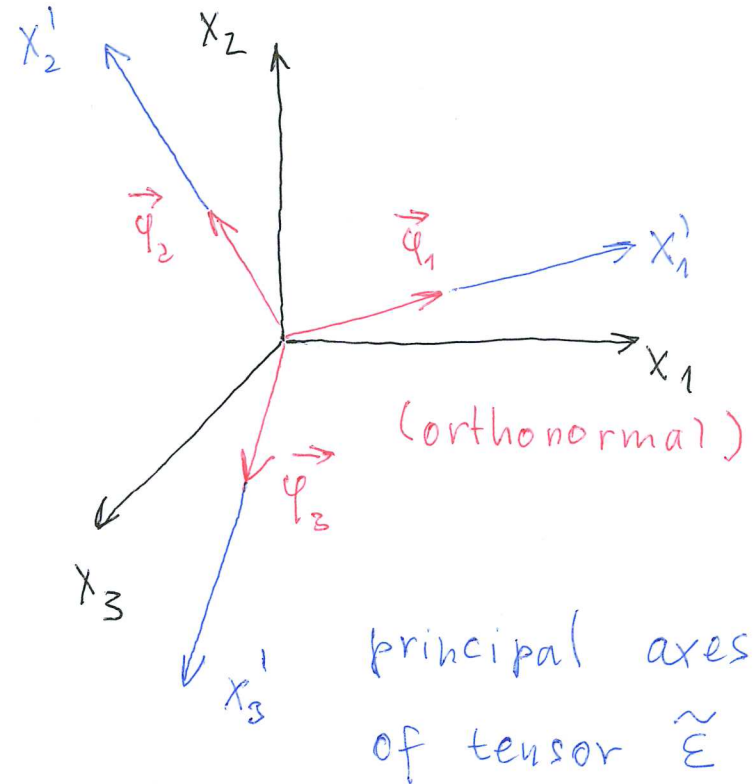
Eigenvalue problem for $k = 1, 2, 3$

$$[\epsilon] \{\varphi_k\} = \lambda_k \{\varphi_k\}$$

principal values: $\epsilon_k \equiv \lambda_k$

principal directions: $\{\varphi_k\}$

$$\vec{\varphi}_1 = \varphi_{11} \vec{e}_1 + \varphi_{12} \vec{e}_2 + \varphi_{13} \vec{e}_3$$





Principal axes

Transformation matrix

$$[A] = \begin{bmatrix} \{\varphi_1\}^T \\ \{\varphi_2\}^T \\ \{\varphi_3\}^T \end{bmatrix} = [\Phi]^T$$



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2nd order tensor

$$[\epsilon'] = [A][\epsilon][A]^T$$



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$$[\epsilon'] = [A][\epsilon][A]^T = [\Phi]^T[\epsilon][\Phi] = [\Phi]^T \underbrace{[\Phi][\Lambda][\Phi]^T}_{[\epsilon]}[\Phi]$$



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$$[\epsilon'] = \mathbf{diag} [\epsilon_1 \epsilon_2 \epsilon_3]$$



Invariants

Invariant function

$$I = f(\epsilon_{ij}) = f(\epsilon'_{ij}) = \text{scalar}$$



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Examples

- trace $\text{tr}(\epsilon) = \epsilon_{11} + \epsilon_{22} + \epsilon_{33} = \epsilon_{ii} = \epsilon'_{jj}$
- principal values $\epsilon_1, \epsilon_2, \epsilon_3$
- principal invariants I_1, I_2, I_3



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- principal values $\epsilon_1, \epsilon_2, \epsilon_3$
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Power invariants

$$\hat{I}_n = \frac{1}{n} \text{tr}(\epsilon^n)$$



Isotropic material

Free energy

$$\psi(\epsilon_{ij}) = \psi(\epsilon_1, \epsilon_2, \epsilon_3)$$



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Chain rule

$$\sigma_{ij} = \frac{\partial \psi}{\partial \epsilon_{ij}}$$



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Chain rule

$$\sigma_{ij} = \frac{\partial \psi}{\partial \hat{I}_1} \frac{\partial \hat{I}_1}{\partial \epsilon_{ij}} + \frac{\partial \psi}{\partial \hat{I}_2} \frac{\partial \hat{I}_2}{\partial \epsilon_{ij}} + \frac{\partial \psi}{\partial \hat{I}_3} \frac{\partial \hat{I}_3}{\partial \epsilon_{ij}}$$



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Derivatives

$$\frac{\partial \hat{I}_1}{\partial \epsilon_{ij}} = \frac{\partial}{\partial \epsilon_{ij}} (\epsilon_{kk})$$



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$$\frac{\partial \hat{I}_1}{\partial \epsilon_{ij}} = \frac{\partial}{\partial \epsilon_{ij}}(\epsilon_{kk}) = \delta_{ik} \delta_{jk} = \delta_{ij}$$



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$$\frac{\partial \hat{I}_1}{\partial \epsilon_{ij}} = \frac{\partial}{\partial \epsilon_{ij}} (\epsilon_{kk}) = \delta_{ik} \delta_{jk} = \delta_{ij}$$

$$\frac{\partial \hat{I}_2}{\partial \epsilon_{ij}} = \frac{\partial}{\partial \epsilon_{ij}} \frac{1}{2} (\epsilon_{kl} \epsilon_{lk})$$



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$$\psi(\epsilon_{ij}) = \psi(\hat{I}_1, \hat{I}_2, \hat{I}_3)$$

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$$\sigma_{ij} = \frac{\partial \psi}{\partial \hat{I}_1} \frac{\partial \hat{I}_1}{\partial \epsilon_{ij}} + \frac{\partial \psi}{\partial \hat{I}_2} \frac{\partial \hat{I}_2}{\partial \epsilon_{ij}} + \frac{\partial \psi}{\partial \hat{I}_3} \frac{\partial \hat{I}_3}{\partial \epsilon_{ij}}$$

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$$\frac{\partial \hat{I}_3}{\partial \epsilon_{ij}} = \frac{\partial}{\partial \epsilon_{ij}} \frac{1}{3} (\epsilon_{pq} \epsilon_{qr} \epsilon_{rp}) = \epsilon_{ik} \epsilon_{kj}$$



General isotropic elasticity

Index notation

$$\sigma_{ij} = \frac{\partial \psi}{\partial \hat{I}_1} \delta_{ij} + \frac{\partial \psi}{\partial \hat{I}_2} \epsilon_{ij} + \frac{\partial \psi}{\partial \hat{I}_3} \epsilon_{ik} \epsilon_{kj}$$



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Direct notation

$$\boldsymbol{\sigma} = \frac{\partial \psi}{\partial \hat{I}_1} \mathbf{I} + \frac{\partial \psi}{\partial \hat{I}_2} \boldsymbol{\epsilon} + \frac{\partial \psi}{\partial \hat{I}_3} \boldsymbol{\epsilon}^2$$

Remark: Cayley-Hamilton theorem



Linear isotropic elasticity

$$\boldsymbol{\sigma} = \frac{\partial \psi}{\partial \hat{I}_1} \mathbf{I} + \frac{\partial \psi}{\partial \hat{I}_2} \boldsymbol{\epsilon} + \frac{\partial \psi}{\partial \hat{I}_3} \boldsymbol{\epsilon}^2$$



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$$\frac{\partial \psi}{\partial \hat{I}_3} = 0 \quad \Rightarrow \quad \psi(\hat{I}_1, \hat{I}_2)$$



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$$\frac{\partial \psi}{\partial \hat{I}_1} = \lambda \hat{I}_1 = \lambda \operatorname{tr}(\boldsymbol{\epsilon})$$



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 \Rightarrow

$$\boldsymbol{\sigma} = \lambda \operatorname{tr}(\boldsymbol{\epsilon}) \mathbf{I} + 2\mu \boldsymbol{\epsilon}$$

(Hooke's law)



Linear isotropic elasticity

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$$\boldsymbol{\sigma} = \lambda \operatorname{tr}(\boldsymbol{\epsilon}) \mathbf{I} + 2\mu \boldsymbol{\epsilon} \quad (\text{Hooke's law})$$

$\lambda, \mu = \text{Lamé}$

convexity: $E, K, G > 0, \nu \in (-1, 0.5)$